

# Functional Mockup Interface 2.0 and HiL Applications

## New Features of FMI 2.0 and beyond

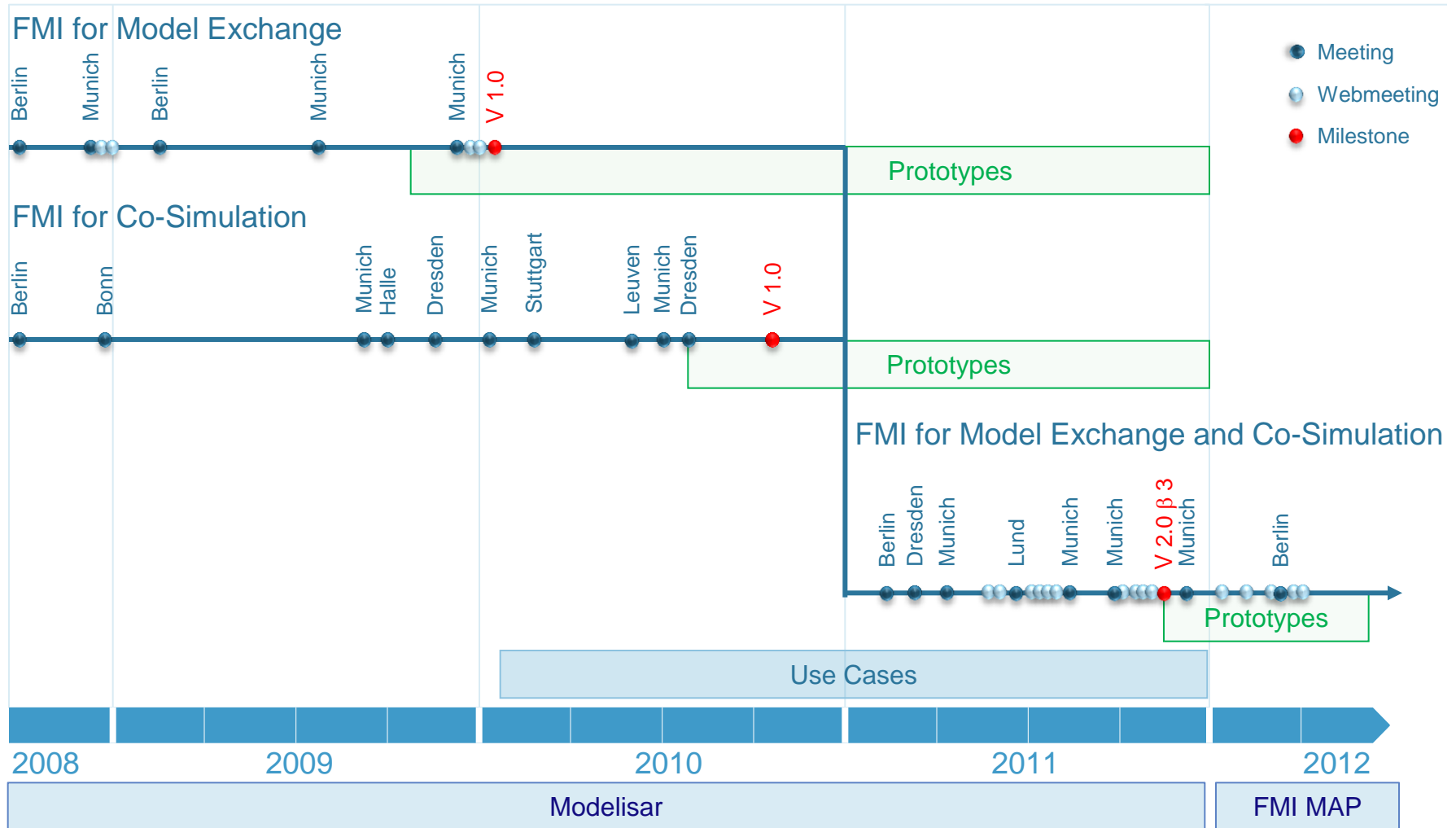
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# New Features of FMI 2.0 and beyond

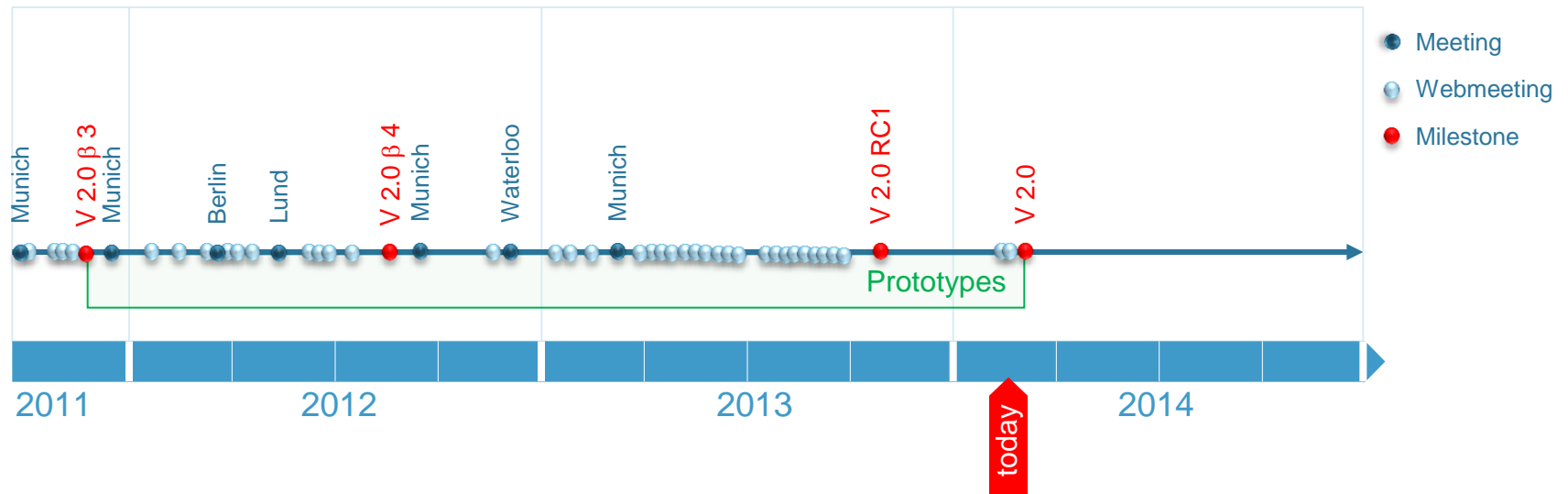
- History
- New Features of FMI 2.0
- Current Status
- Future Plans

# Development Process



# Development Process

## FMI for Model Exchange and Co-Simulation



## FMI 2.0:

- Valid for several years
- Backwards-compatible enhancements in minor releases

# New features of FMI 2.0

Clarification of specification:

- Instantiation
- Classification of variables
- Mathematical model
- Calling sequence

Features:

- Improved initialization
- Semantics of event handling
- Tunable parameters
- Improved unit handling
- Save and restore FMU state
- Detailed dependency information (inputs, outputs, derivatives)
- Efficient interface to Jacobian matrices

# FMI 2.0

## Harmonization

### FMI 1.0:

- `fmiInstantiateModel, fmiInstantiateSlave`

### FMI 2.0:

- `fmiInstantiate(..., fmiType fmuType,...)`
- With `fmiType`: `fmiModelExchange` **or** `fmiCoSimulation`
- Allows for extensions without disturbing existing semantics
- E.g.: Hybrid Co-Simulation, Observers

# FMI 2.0

## Classification of interface variables

### causality

- parameter
- input: output of another model
- output: input for another model
- local: not to be used by other models

### variability

- constant
  - fixed: constant after initialization
  - tunable: constant between events
  - discrete: changes at event instances
  - continuous
- 
- Combination of `causality` and `variability` allows clear classification of all kinds of variables
  - New: distinction between `tunable` and `fixed` parameters
    - Stop simulation, set tunable parameters, resume simulation

# FMI 2.0

## Initialization, Events

### FMI 1.0:

- Only one function call for initialization: `fmiInitialize`
- No iteration during initialization possible
- Critical, if initial conditions depend on variables in algebraic loops

### FMI 2.0:

- Introduction of “Initialization Mode” (`fmiEnterInitializationMode`, `fmiExitInitializationMode`)
- Solution of algebraic loops by calling of `fmiSetXX`, `fmiGetXX` in the same way as in “Continuous Time Mode”
- For Model Exchange and Co-Simulation
- Introduction of “Event Mode” and a semantics for enter, exit and setting of new discrete state



# FMI 2.0

## Save and Restore FMU State

- FMI 1.0: implicate save and restore depending on arguments of `fmiDoStep`
- FMI 2.0: explicite function calls for Model Exchange and Co-Simulation

```
fmiStatus fmiGetFMUstate(fmiComponent c, fmiFMUstate* FMUstate)
fmiStatus fmiSetFMUstate(fmiComponent c, fmiFMUstate FMUstate)
```
- Iterative Co-Simulation algorithms
  - Repeat more than one communication step
- Model Predictive Control
  - Simulate some steps starting from the same state with different sets of input values
  - Use the optimal set as control value for the real system
- FMU state can be serialized into a byte vector
  - Usage: start a training simulator from a certain scenario

# FMI 2.0

## Dependency Information

FMI 1.0:

- Only dependencies of outputs on inputs can be indicated

FMI 2.0:

- Dependencies of outputs on continuous states
- Dependencies of derivatives on continuous states and inputs

Usage:

- Detection of algebraic loops
- Definition of sparsity pattern of Jacobian matrices

# FMI 2.0

## Dependency Information

Kind of dependency is also defined:

- `nonlinear`: Jacobian entry is not constant
- `fixed`: Jacobian entry is constant
- `discrete`: Jacobian entry may change after events

Allows optimizations:

- Generate linear systems of equations for solution of algebraic loops if possible
- Reduce number of Jacobian computations

# FMI 2.0

## Partial Derivatives, Jacobian Matrices

- Jacobians are needed for:
  - Implicit integration methods
  - Solution of systems of equations resulting from algebraic loops
  - Linearization of FMU
  - Extended Kalman filters
- Numerical computation is expensive for large models
- Optional function for obtaining directional derivatives
  - `fmiGetDirectionalDerivative`
  - Allows obtaining of single directional derivatives, spares or dense Jacobian

# Current Status

- October 2013: Release of FMI 2.0 Release Candidate1
- FMI 2.0 will be released as soon as test cases are passed by a certain number of tools
- 8 tool vendors are involved in testing:
  - **AVL**: Import of Model Exchange and Co-Simulation FMUs, export in in development
  - **Dassault (Dymola)**: Exported test FMUs are available on SVN, FMU test library runs successful
  - **dSPACE**: Successful running of Co-Simulation FMUs (Dymola, **MapleSim**, SimulationX) in source code and binary form in SCALEXIO and VEOS
  - **ITI (SimulationX)**: Exported Test FMUs are available on SVN, import is in development
  - **QTronic**: Import of FMUs from SimulationX into Silver, Release of FMU SDK 2.0.0
  - **Modelon**: FMU Checker for FMI 2.0 RC1 is available, FMI library is updated, FMI Export for JModelica is nearly finished

# Current Status

- No major concerns have been reported until now
- Some tickets for minor improvement of specification have been filed
- FMI Design meetings are scheduled for the next weeks:
  - Presentation and discussion of test results
  - Working on filed tickets
  - Decision about release
- Offers for FMI-logo have been from seven international design studios

# Future Plans

- Backwards-compatible extensions (FMI 2.1):
  - Handling of clocked and sampled data systems
  - Hybrid Co-Simulation
  - Observers
  - Support of arrays
  - Hierarchical (structured) data
  - Bus and physical connectors
  - DAE representation
  - Graphical appearance